# PAPER On the Three-Dimensional Channel Routing

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**SUMMARY** The 3-D channel routing is a fundamental problem on the physical design of 3-D integrated circuits. The 3-D channel is a 3-D grid *G* and the terminals are vertices of *G* located in the top and bottom layers. A net is a set of terminals to be connected. The objective of the 3-D channel routing problem is to connect the terminals in each net with a Steiner tree (wire) in *G* using as few layers as possible and as short wires as possible in such a way that wires for distinct nets are disjoint. This paper shows that the problem is intractable. We also show that a sparse set of  $\nu$  2-terminal nets can be routed in a 3-D channel with  $O(\sqrt{\nu})$  layers using wires of length  $O(\sqrt{\nu})$ .

key words: 3-D channel, NP-complete, routing algorithm, Steiner tree

#### 1. Introduction

The three-dimensional (3-D) integration is an emerging technology to implement large circuits, and currently being extensively investigated. (See [2]–[4], [7], [9], [14], [16], [19], [22] for example.) In this paper, we consider a problem on the physical design of 3-D integrated circuits.

The 3-D channel routing is a fundamental problem on the physical design of 3-D integrated circuits. The 3-D channel is a 3-D grid *G* consisting of *columns*, *rows*, and *layers* which are rectilinear grid planes defined by fixing *x*-, *y*-, and *z*-coordinates at integers, respectively. The numbers of columns, rows, and layers are called the *width*, *depth*, and *height* of *G*, respectively. (See Fig. 1.) *G* is called a (W, D, H)-channel if the width is *W*, depth is *D*, and height is *H*. A vertex of *G* is a grid point with integer coordinates. We assume without loss of generality that the vertex set of a (W, D, H)-channel is  $\{(x, y, z) \mid x \in [W], y \in [D], z \in [H]\}$ , where  $[i] = \{1, 2, ..., i\}$  for a positive integer *i*. Layers defined by z = H and z = 1 are called the *top* and *bottom layers*, respectively.

A *terminal* is a vertex of G located on the top or bottom layer. A *net* is a set of terminals to be connected. A net containing k terminals is called a *k-net*. The object of the 3-D channel routing problem is to connect the terminals in each net with a Steiner tree (wire) in G using as few layers as possible and as short wires as possible in such a way that

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Steiner trees spanning distinct nets are vertex-disjoint. A set of nets is said to be *routable* in *G* if *G* has vertex-disjoint Steiner trees spanning the nets.

We first show in Sect. 2 that the 3-D channel routing problem is intractable. We next show in Sect. 3 that if G is a (2n, 2n, 3n+1)-channel, the terminals are located on vertices with odd x- and y-coordinates, and each net has terminals both on the top and bottom layers, then any set of  $n^2$  2-nets is routable in G. We finally show in Sect. 4 some lower bounds for the height of a 3-D channel routing for 2-nets. In particular, we show that there exists a set of  $n^2$  such 2-nets that cannot be routed in a (2n, 2n, n/2 - 1)-channel.

#### 2. Intractability

We consider in this section the complexity of the following decision problem associated with the 3-D channel routing problem.

#### **3-D CHANNEL ROUTING**

INSTANCE: Positive integers W, D, H, a set of terminals  $T \subseteq \{(x, y, z) \mid x \in [W], y \in [D], z \in \{1, H\}\}$  and a partition of T into nets  $N_1, N_2, \ldots, N_y$ .

QUESTION: Is a set of nets  $\{N_1, N_2, ..., N_\nu\}$  routable in a (W, D, H)-channel?

We have two well-known problems as subproblems of 3-D CHANNEL ROUTING, namely, ONE-ROW CHAN-NEL ROUTING and TWO-ROW CHANNEL ROUTING. These problems can be stated as follows.

#### ONE-ROW CHANNEL ROUTING

INSTANCE: Positive integers W, H, a set of terminals

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 $T \subseteq \{(x, 1, z) \mid x \in [W], z \in \{1, H\}\}$  and a partition of *T* into nets  $N_1, N_2, \dots, N_v$ .

QUESTION: Is a set of nets  $\{N_1, N_2, ..., N_\nu\}$  routable in a (W, 1, H)-channel?

### TWO-ROW CHANNEL ROUTING

INSTANCE: Positive integers W, H, a set of terminals  $T \subseteq \{(x, 1, z) \mid x \in [W], z \in \{1, H\}\}$  and a partition of T into nets  $N_1, N_2, \ldots, N_{\nu}$ .

QUESTION: Is a set of nets  $\{N_1, N_2, \dots, N_{\nu}\}$  routable in a (W, 2, H)-channel?

It should be noted that TWO-ROW CHANNEL ROUTING has been known as "UNRESTRICTED" TWO-LAYER CHANNEL ROUTING in the literature. The complexity of TWO-ROW CHANNEL ROUTING is a longstanding open question posed by Johnson [10], while ONE-ROW CHAN-NEL ROUTING can be solved in polynomial time as shown by Dolev, Karplus, Siegel, Strong, and Ullman [8].

The purpose of this section is to show the following.

**Theorem 1:** 3-D CHANNEL ROUTING is NP-hard even for 2-nets. □

The complexity of TWO-ROW CHANNEL ROUT-ING is still open. Moreover, the complexity of the following problem is open for any fixed integer  $d \ge 2$ .

### 2.5-D CHANNEL ROUTING

INSTANCE: Positive integers W, H, a set of terminals  $T \subseteq \{(x, y, z) \mid x \in [W], y \in [d], z \in \{1, H\}\}$  and a partition of T into nets  $N_1, N_2, \ldots, N_v$ .

QUESTION: Is a set of nets  $\{N_1, N_2, \dots, N_{\nu}\}$  routable in a (W, d, H)-channel?

The 3-D channel routing for 2-nets is closely related to the  $(n^2 - 1)$ -puzzle defined below.

# 2.1 $(n^2 - 1)$ -Puzzle

The  $(n^2 - 1)$ -puzzle is a generalization of the well-known 15-puzzle [12]. The  $(n^2 - 1)$ -puzzle is played on an  $n \times n$ board,  $n \ge 2$ . There are  $n^2$  distinct tiles on the board: one *blank tile* and  $n^2 - 1$  tiles numbered from 1 to  $n^2 - 1$ . Each of the  $n^2$  square locations of the board is occupied by exactly one tile. An instance of  $(n^2 - 1)$ -puzzle consists of two board configurations C (the *initial configuration*) and C' (the *final* configuration). A move is an exchange of the blank tile with a nonblank tile located on a horizontally or vertically adjacent location. The goal of the puzzle is to find a sequence of moves that transforms C to C'. The configuration C' is said to be *reachable* from C if there exists such a sequence of moves. Notice that C' is reachable from C if and only if Cis reachable from C'. The configurations C and C' are said to be *reachable* with h moves if there exists a sequence of at most h moves that transforms C to C'. Figure 2 shows two unreachable configurations of 15-puzzle. This is the original 15-puzzle of Loyd [12]. Our problem is to find a shortest





sequence of moves that transforms C to C' if C and C' are reachable. The corresponding decision problem is described as follows.

 $(n^2 - 1)$ -PUZZLE

INSTANCE: Two  $n^2$  board configurations *C* and *C'*, and a positive integer *h*.

QUESTION: Are C and C' reachable with h moves?

Ratner and Warmuth [15] showed the following.

**Theorem I**  $(n^2 - 1)$ -PUZZLE is NP-complete.  $\Box$ 

2.2 Proof of Theorem 1

We reduce  $(n^2-1)$ -PUZZLE to 3-D CHANNEL ROUTING. The  $(n^2 - 1)$ -puzzle is naturally associated with a 3-D channel routing for 2-nets as follows. The configurations *C* and *C'* are corresponding to the top and bottom layers. A terminal is corresponding to a location of a nonblank tile on *C* or *C'*. A pair of locations of a nonblank tile on *C* and *C'* is corresponding to a 2-net.

**Lemma 1:** Configurations C and C' of  $(n^2 - 1)$ -puzzle are reachable with h moves for  $h \ge 2$  if and only if the 2-nets corresponding to the nonblank tiles are routable in an (n, n, h)-channel.

*Proof.* Suppose that configurations *C* and *C'* of  $(n^2 - 1)$ -puzzle are reachable with *h* moves for  $h \ge 2$ . For a sequence of moves that transforms *C* to *C'*, locations in the sequence for a nonblank tile correspond to part of the wire connecting the terminals of the corresponding 2-net. Since such wires are vertex-disjoint, the 2-nets corresponding to the nonblank tiles are routable in an (n, n, h)-channel.

Conversely, suppose that the 2-nets corresponding to the nonblank tiles are routable in an (n, n, h)-channel with  $h \ge 2$ . Since the number of 2-nets is  $n^2 - 1$ , every wire is descending with respect to the *z*-coordinate, and for every layer, at most one edge of the layer is contained in the wires. Since such an edge corresponds to a move, the corresponding configurations of  $(n^2 - 1)$ -puzzle are reachable with *h* moves.

Lemma 1 implies a polynomial time reduction from  $(n^2 - 1)$ -PUZZLE to 3-D CHANNEL ROUGING. Thus we

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conclude that 3-D CHANNEL ROUTING is NP-hard by Theorem I. This completes the proof of Theorem 1.

**Example 1:** For initial and final configurations  $C_1$  and  $C_2$  of 15-puzzle shown in Fig. 3, the corresponding 2-nets are shown in Fig. 4. A sequence of 3 moves that transforms  $C_1$  to  $C_2$ , and the corresponding 3-D channel routing with height 3 are shown in Fig. 5.

#### 3. Sparse Instances

Let G be a  $(2\sqrt{v}, 2\sqrt{v}, H)$ -channel with a set

$$\mathcal{N} = \left\{ \{ (X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle}, 1) \} \mid X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle} \text{ are odd integers in } [2\sqrt{\nu}], k \in [\nu] \right\}$$

of v 2-nets. N is said to be *sparse*. The purpose of this section is to show the following.

**Theorem 2:** Any sparse N can be routed in a  $(2\sqrt{\nu}, 2\sqrt{\nu}, 3\sqrt{\nu} + 1)$ -channel using wires of length  $O(\sqrt{\nu})$  in  $O(\nu \log \nu)$  time.  $\Box$ 

We need some preliminaries to prove the theorem.

#### 3.1 3-D Channels

We consider a 3-D channel of height  $H = 3\sqrt{v} + 1$ , which is a  $2\sqrt{v} \times 2\sqrt{v} \times H$  3-D grid. Each grid point is denoted by (x, y, z) with  $x, y \in [2\sqrt{v}]$  and  $z \in [H]$ . The column, row, and layer defined by x = X, y = Y, and z = Z are called the *X*-column, *Y*-row, and *Z*-layer, respectively. The



(a) Sequence of 3 moves that transforms  $C_1$  to  $C_2$ .



(b) Corresponding 3-D channel routing with height 3.

Fig. 5 Correspondence between 15-puzzle and 3-D channel routing.

*H*-layer and 1-layer correspond to the top and bottom layers, respectively. Let  $\mathcal{N} = \{N_k \mid k \in [\nu]\}$  be a sparse set of  $\nu$  2-nets, and let  $(X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H)$  and  $(X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle}, 1)$  be the terminals of  $N_k$  ( $k \in [\nu]$ ), such that  $X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, X_k^{\langle 1 \rangle}$ , and  $Y_k^{\langle 1 \rangle}$  are odd, and that  $(X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H) \neq (X_{k'}^{\langle H \rangle}, Y_{k'}^{\langle H \rangle}, H)$  and  $(X_k^{\langle 1 \rangle}, Y_{k'}^{\langle 1 \rangle}, 1) \neq (X_{k'}^{\langle 1 \rangle}, Y_{k'}^{\langle 1 \rangle}, 1)$  if  $k \neq k'$ .

#### 3.2 2-Row Channel Routings

We consider in this section the 2-row channel routing which is used as a subroutine of our 3-D channel routing algorithm. A 2-row channel of height m + 1 is a  $2m \times 2 \times (m + 1)$  3-D grid G'. Let  $\mathcal{N}' = \{N'_k \mid k \in [m]\}$  be a sparse set of m 2-nets, and let  $(X_k^{(m+1)}, 1, m + 1)$  and  $(X_k^{(1)}, 1, 1)$  be the terminals of  $N'_k$  ( $k \in [m]$ ), where  $X_k^{(m+1)}$  and  $X_k^{(1)}$  are odd, and  $X_k^{(m+1)} \neq X_{k'}^{(m+1)}$  and  $X_k^{(1)} \neq X_{k'}^{(1)}$  if  $k \neq k'$ .

**Lemma 2:** Any sparse  $\mathcal{N}'$  can be routed in G' so that no wire passes through the top layer.

*Proof.* Let  $p_1, p_2, ..., p_l$  be grid points of G' such that  $p_i$  and  $p_{i+1}$  differ in just one coordinate,  $i \in [l-1]$ . Then,

we denote by  $[p_1, p_2, \ldots, p_l]$  a wire connecting  $p_1$  and  $p_l$ obtained by connecting  $p_i$  and  $p_{i+1}$  by an axis-parallel line segment,  $i \in [l-1]$ . If  $X_k^{(m+1)} = X_k^{(1)}$  for all  $k \in [m]$ , the lemma clearly holds. Suppose without loss of generality that  $X_k^{(m+1)} = X_k^{(m+1)}$  $X_1^{(m+1)} = X_2^{(1)}$ . Then, if  $m \ge 3$ ,  $\mathcal{N}'$  can be routed in G' using a wire defined by

$$\begin{split} & \left[ \left( X_{1}^{\langle m+1 \rangle}, 1, m+1 \right), \left( X_{1}^{\langle m+1 \rangle}, 1, m \right), \left( X_{1}^{\langle m+1 \rangle} +1, 1, m \right), \\ & \left( X_{1}^{\langle m+1 \rangle} +1, 1, 1 \right), \left( X_{1}^{\langle m+1 \rangle} +1, 2, 1 \right), \left( X_{1}^{\langle 1 \rangle}, 2, 1 \right), \\ & \left( X_{1}^{\langle 1 \rangle}, 1, 1 \right) \right] \end{split}$$

for  $N'_1$ , a wire defined by

$$\begin{bmatrix} (X_2^{(m+1)}, 1, m+1), (X_2^{(m+1)}, 1, 2), (X_2^{(m+1)}, 2, 2), \\ (X_2^{(1)}, 2, 2), (X_2^{(1)}, 1, 2), (X_2^{(1)}, 1, 1) \end{bmatrix}$$

for  $N'_2$ , and wires defined by

$$\begin{split} & \left[ \left( X_{k}^{\langle m+1 \rangle}, 1, m+1 \right), \left( X_{k}^{\langle m+1 \rangle}, 1, k \right), \left( X_{k}^{\langle m+1 \rangle}, 2, k \right), \\ & \left( X_{k}^{\langle 1 \rangle} + 1, 2, k \right), \left( X_{k}^{\langle 1 \rangle} + 1, 1, k \right), \left( X_{k}^{\langle 1 \rangle} + 1, 1, 1 \right), \\ & \left( X_{k}^{\langle 1 \rangle}, 1, 1 \right) \right] \end{split}$$

for  $N'_k$ ,  $3 \le k \le m$ . It is easy to see that the wires defined above are disjoint. If m = 2, N' can be routed in G' as shown in Fig. 6. In either case, no wire passes through the top layer.

The routing defined in the proof of Lemma 2 is called a  $\tau$ -routing for  $\mathcal{N}'$ . It is easy to see that a  $\tau$ -routing for a sparse set of v 2-nets can be computed in O(v) time. An example of  $\tau$ -routing is shown in Fig. 7. Now, we are ready to prove Theorem 2.



Fig. 6 A routing for a set of two 2-nets.



#### Proof of Theorem 2 3.3

#### 3.3.1 Virtual Terminals

We introduce in this section virtual terminals to compute a routing for a sparse set

$$\mathcal{N} = \left\{ N_k = \{ (X_k^{\langle 3\sqrt{\nu}+1 \rangle}, Y_k^{\langle 3\sqrt{\nu}+1 \rangle}, 3\sqrt{\nu}+1), (X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle}, 1) \} \right|$$
$$X_k^{\langle 3\sqrt{\nu}+1 \rangle}, Y_k^{\langle 3\sqrt{\nu}+1 \rangle}, X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle} \text{ are odd integers in } [2\sqrt{\nu}],$$
$$k \in [\nu] \right\}$$

of 2-nets in a  $(2\sqrt{\nu}, 2\sqrt{\nu}, 3\sqrt{\nu}+1)$ -channel. Let  $H = 3\sqrt{\nu}+1$ 1,  $L = 2\sqrt{\nu} + 1$ , and  $M = \sqrt{\nu} + 1$  for simplicity. By the definition of  $\mathcal{N}$ ,

$$|\{k \in [\nu] \mid X_k^{\langle H \rangle} = 2j - 1\}| = \sqrt{\nu} \text{ and}$$
(1)

$$|\{k \in [\nu] \mid X_k^{(1)} = 2j - 1\}| = \sqrt{\nu}.$$
 (2)

We use two virtual terminals  $(X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L)$  and  $(X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M)$  for each net  $N_k$ . A set of virtual terminals  $\{(X_k^{\langle L \rangle}, Y_k^{\langle L \rangle},$ L),  $(X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M) \mid k \in [v]$  is said to be *feasible* if the following conditions are satisfied:

 $\begin{array}{ll} (\mathrm{i}) & X_k^{\langle L \rangle} = X_k^{\langle H \rangle} \text{ for any } k \in [\nu]; \\ (\mathrm{ii}) & Y_k^{\langle L \rangle} = Y_k^{\langle M \rangle} \text{ for any } k \in [\nu]; \\ (\mathrm{iii}) & X_k^{\langle M \rangle} = X_k^{\langle 1 \rangle} \text{ for any } k \in [\nu]; \\ (\mathrm{iv}) & (X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L) \neq (X_h^{\langle L \rangle}, Y_h^{\langle L \rangle}, L) \text{ if } k \neq h; \\ (\mathrm{v}) & (X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M) \neq (X_h^{\langle M \rangle}, Y_h^{\langle M \rangle}, M) \text{ if } k \neq h. \end{array}$ 

**Lemma 3:** For any sparse set N of 2-nets, there exists a feasible set of virtual terminals  $\{(X_k^{(L)}, Y_k^{(L)}, L), (X_k^{(M)}, Y_k^{(M)}), K_k^{(M)}, K_k^{($ M) |  $k \in [v]$ }. Moreover, these virtual terminals can be computed in  $O(v \log v)$  time.

*Proof.* For every  $k \in [\nu]$ ,  $Y_k^{\langle L \rangle} = Y_k^{\langle M \rangle}$  is determined as follows. Let *B* be a bipartite multigraph defined as follows:

$$\begin{split} V(B) &= \{(2j-1,z) \mid j \in [\sqrt{\nu}], z \in \{1,H\}\};\\ E(B) &= \left\{ \left( (X_k^{\langle H \rangle},H), (X_k^{\langle 1 \rangle},1) \right) \mid \\ &\quad \left\{ (X_k^{\langle H \rangle},Y_k^{\langle H \rangle},H), (X_k^{\langle 1 \rangle},Y_k^{\langle 1 \rangle},1) \right\} \in \mathcal{N} \right\}. \end{split}$$

For each  $j \in [\sqrt{\nu}]$ , there exist exactly  $\sqrt{\nu}$  2-nets

$$\{(X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle}, 1)\}$$

such that  $X_k^{\langle H \rangle} = 2j - 1$  by (1), and exactly  $\sqrt{\nu}$  2-nets

$$\{(X_k^{\langle H\rangle},Y_k^{\langle H\rangle},H),(X_k^{\langle 1\rangle},Y_k^{\langle 1\rangle},1)\}$$

such that  $X_k^{(1)} = 2j - 1$  by (2). Therefore, *B* is  $\sqrt{\nu}$ -regular. A  $\sqrt{v}$ -regular bipartite multigraph has a  $\sqrt{v}$ -edge-coloring by König's theorem [11]. Moreover, such a  $\sqrt{v}$ -edge-coloring can be computed in  $O(|E(B)| \log |E(B)|) = O(v \log v)$  time [1], [5], [6]. Let  $c : E(B) \to [\sqrt{\nu}]$  be such an edge-coloring. If  $c_k$  is the color assigned to edge  $((X_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, 1))$ , we



**Fig. 8** An example of a (10, 10, 16)-grid G and its subgrids.

define  $Y_k^{\langle L \rangle} = Y_k^{\langle M \rangle} = 2c_k - 1$ . We also define  $X_k^{\langle L \rangle} = X_k^{\langle H \rangle}$ and  $X_k^{\langle M \rangle} = X_k^{\langle 1 \rangle}$  for every  $k \in [\nu]$ . Then, the following set

$$\mathcal{V} = \left\{ (X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L), (X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M) \mid k \in [\nu] \right\}$$

is a feasible set of virtual terminals for  $\mathcal{N}$ . By definition,  $\mathcal{V}$  satisfies (i), (ii), and (iii). If  $X_k^{\langle L \rangle} = X_h^{\langle L \rangle}$  then  $X_k^{\langle H \rangle} = X_h^{\langle H \rangle}$ . Thus, edges  $((X_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, 1))$  and  $((X_h^{\langle H \rangle}, H), (X_h^{\langle 1 \rangle}, 1))$  of B have different colors, and we have  $Y_k^{\langle L \rangle} \neq Y_h^{\langle L \rangle}$ . Thus  $\mathcal{V}$  satisfies (iv). If  $X_k^{\langle M \rangle} = X_h^{\langle M \rangle}$  then  $X_k^{\langle 1 \rangle} = X_h^{\langle 1 \rangle}$ . Thus, edges  $((X_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, 1))$  and  $((X_h^{\langle H \rangle}, H), (X_h^{\langle 1 \rangle}, 1))$  of B have different colors, and we have  $Y_k^{\langle M \rangle} \neq Y_h^{\langle M \rangle}$ . Thus  $\mathcal{V}$  satisfies (v), and we conclude that  $\mathcal{V}$  is feasible.

Since the construction of *B* takes O(v) time and computation of *c* takes  $O(v \log v)$  time, we have the lemma.

## 3.3.2 Polynomial Time Algorithm

Let  $G_{*j}^{\langle r \rangle}$  be a  $2 \times 2 \sqrt{\nu} \times (\sqrt{\nu} + 1)$ -subgrid induced by a set of grid points:

$$\{(x, y, z) \mid x \in \{2j - 1, 2j\}, y \in [2\sqrt{\nu}], r \le z \le r + \sqrt{\nu}\},\$$

and  $G_{i*}^{(r)}$  be a subgrid induced by a set of grid points:

$$\left\{(x, y, z) \mid x \in \left[2\sqrt{\nu}\right], y \in \{2i - 1, 2i\}, r \le z \le r + \sqrt{\nu}\right\}.$$

We decompose the 3-D grid into  $3\sqrt{\nu}$  subgrids  $G_{*j}^{\langle L \rangle}$  for  $j \in [\sqrt{\nu}]$ ,  $G_{i*}^{\langle M \rangle}$  for  $i \in [\sqrt{\nu}]$ , and  $G_{*j}^{\langle 1 \rangle}$  for  $j \in [\sqrt{\nu}]$ , as shown in Fig. 8. By Lemma 3, we have a feasible set of virtual terminals:

$$\mathcal{V} = \{(X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L), (X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M) \mid k \in [\nu]\}.$$

We define three sets of 2-nets as follows:

$$\begin{split} \mathcal{N}_{*j}^{\langle L \rangle} &= \{N_k^{\langle H, L \rangle} = \{(X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H), (X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L)\} \mid \\ & X_k^{\langle H \rangle} = 2j - 1\}, \\ \mathcal{N}_{i*}^{\langle M \rangle} &= \{N_k^{\langle L, M \rangle} = \{(X_k^{\langle L \rangle}, Y_k^{\langle L \rangle}, L), (X_k^{\langle M \rangle}, Y_k^{\langle M \rangle}, M)\} \mid \end{split}$$

Fig. 9 3-D channel routing algorithm.

$$Y_{k}^{\langle L \rangle} = 2i - 1\}, \text{ and}$$
$$\mathcal{N}_{*j}^{\langle 1 \rangle} = \{N_{k}^{\langle M, 1 \rangle} = \{(X_{k}^{\langle M \rangle}, Y_{k}^{\langle M \rangle}, M), (X_{k}^{\langle 1 \rangle}, Y_{k}^{\langle 1 \rangle}, 1)\} \mid X_{k}^{\langle 1 \rangle} = 2j - 1\}.$$

Since  $\mathcal{V}$  is feasible, the terminals of 2-nets in  $\mathcal{N}_{*j}^{\langle L \rangle}$  are contained in  $G_{*j}^{\langle L \rangle}$ , and so  $\mathcal{N}_{*j}^{\langle L \rangle}$  is routable in  $G_{*j}^{\langle L \rangle}$  by using  $\tau$ -routing for each  $j \in [\sqrt{\nu}]$ . Similarly,  $\mathcal{N}_{i*}^{\langle M \rangle}$  is routable in  $G_{i*}^{\langle M \rangle}$  by using  $\tau$ -routing for each  $i \in [\sqrt{\nu}]$ , and  $\mathcal{N}_{*j}^{\langle 1 \rangle}$  is routable in  $G_{*i}^{\langle M \rangle}$  by using  $\tau$ -routing for each  $j \in [\sqrt{\nu}]$ .

routable in  $G_{*j}^{\langle 1 \rangle}$  by using  $\tau$ -routing for each  $j \in [\sqrt{\nu}]$ . A wire for each 2-net  $N_k$  in  $\mathcal{N}$  is obtained by concatenating three wires  $N_k^{\langle H,L \rangle}$ ,  $N_k^{\langle L,M \rangle}$ , and  $N_k^{\langle M,1 \rangle}$ .

Our 3-D channel routing algorithm is shown in Fig. 9. It is straightforward that N is routed in a 3-D channel of height  $3\sqrt{\nu} + 1$ . Since the length of every wire of a  $\tau$ -routing is at most  $3\sqrt{\nu} + 4$ , the maximum wire length of our 3-D channel routing algorithm is at most  $9\sqrt{\nu} + 12$ .

It should be noted that the time complexity of our 3-D channel routing algorithm is  $O(v \log v)$ , since Step 0 takes  $O(v \log v)$  time, and other steps take O(v) time as easily seen. This completes the proof of Theorem 2.

#### 4. Lower Bounds

We investigate in this section some lower bounds for the height of 3-D channel routing. We assume for simplicity that G is an (S, S, H)-channel, and

$$\mathcal{N} = \{N_k = \{(x_k^t, y_k^t, H), (x_k^b, y_k^b, 1)\} \mid k \in [\nu]\}$$

is a set of v 2-nets, where  $v < S^2$ , and  $H \ge 2$ .

#### 4.1 Densities

Our first lower bound is the *layer density*  $\Delta_{\text{lay}}(N)$  which is defined as follows:

$$\Delta_{\text{lay}}(\mathcal{N}) = \frac{\sum_{k=1}^{\nu} \left( |x_k^t - x_k^b| + |y_k^t - y_k^b| \right)}{S^2 - \nu}.$$

**Theorem 3:** If  $\mathcal{N}$  is routable in G then  $H \ge \lceil \Delta_{\text{lay}}(\mathcal{N}) \rceil$ .

*Proof.* Since the length of a shortest path connecting terminals of  $N_k$  is  $|x_k^t - x_k^b| + |y_k^t - y_k^b| + H - 1$ , any routing of  $N_k$  in *G* contains  $|x_k^t - x_k^b| + |y_k^t - y_k^b| + H$  grid points. Thus,

$$\sum_{k=1}^{\nu} \left( |x_k^t - x_k^b| + |y_k^t - y_k^b| + H \right) \le S^2 H,$$

and we have  $H \ge \Delta_{\text{lay}}(N)$ . Since *H* is an integer,  $H \ge \lceil \Delta_{\text{lay}}(N) \rceil$  and we have the theorem.  $\Box$ 

In Figs. 10 and 11, terminals of a net  $N_k$  are denoted by k. It is easy to see that  $\Delta_{\text{lay}}(N_a) = 28$ , and  $\Delta_{\text{lay}}(N_b) = 3/5$ .

Our second lower bound is the *global density*  $\Delta_{glo}(N)$ 







**Fig. 11**  $\mathcal{N}_b$  such that  $\Delta_{\text{glo}}(\mathcal{N}_b)$  dominates  $\Delta_{\text{lay}}(\mathcal{N}_b)$  and  $\Delta_{\text{loc}}(\mathcal{N}_b)$ .

which is defined as follows. Let  $R_1, R_2, ..., R_S$  be the rows of G, and  $C_1, C_2, ..., C_S$  be the columns of G (See Figs. 10 and 11). For any  $i, j \in [\nu]$ , let

$$T^{t}(R_{i}) = \{(x_{k}^{t}, y_{k}^{t}, H) \mid k \in [\nu], y_{k}^{t} = i\},\$$

$$T^{b}(R_{i}) = \{(x_{k}^{b}, y_{k}^{b}, 1) \mid k \in [\nu], y_{k}^{b} = i\},\$$

$$\mathcal{N}(R_{i}) = \{N_{k} \mid k \in [\nu], (y_{k}^{t} - i)(y_{k}^{b} - i) < 0\},\$$

$$T^{t}(C_{j}) = \{(x_{k}^{t}, y_{k}^{t}, H) \mid k \in [\nu], x_{k}^{t} = j\},\$$

$$T^{b}(C_{j}) = \{(x_{k}^{b}, y_{k}^{b}, 1) \mid k \in [\nu], x_{k}^{b} = j\},\$$
and
$$\mathcal{N}(C_{j}) = \{N_{k} \mid k \in [\nu], (x_{k}^{t} - j)(x_{k}^{b} - j) < 0\}.$$

The following is immediate.

**Lemma 4:** A wire of any net in  $\mathcal{N}(R_i)$  [ $\mathcal{N}(C_j)$ ] contains a vertex of  $R_i$  [ $C_j$ ].

Let  $d(R_i) [d(C_j)]$  be the sum of the number of terminals on  $R_i [C_j]$  and the number of 2-nets which have a terminal on both sides of  $R_i [C_j]$ , that is,

$$d(R_i) = |T^t(R_i)| + |T^b(R_i)| + |\mathcal{N}(R_i)|, \text{ and}$$
(3)

$$d(C_j) = |T^t(C_j)| + |T^b(C_j)| + |\mathcal{N}(C_j)|.$$
(4)

Notice that

$$T^{t}(R_{i}) \cup T^{b}(R_{i}) \subseteq V(R_{i}), \text{ and}$$
 (5)

$$T^{\iota}(C_j) \cup T^{\nu}(C_j) \subseteq V(C_j).$$
(6)

We define that:

$$\Delta_{\text{glo}}(\mathcal{N}) = \max\left\{\frac{\max\left\{d(R_i) \mid i \in [S]\right\}}{S}, \frac{\max\left\{d(C_j) \mid j \in [S]\right\}}{S}\right\}.$$

**Theorem 4:** If  $\mathcal{N}$  is routable in G then  $H \ge \lceil \Delta_{\text{glo}}(\mathcal{N}) \rceil$ .

*Proof.* From Lemma 4, (3), and (5), we have  $d(R_i) \le |V(R_i)| = SH$  for any  $i \in [\nu]$ , since wires are vertex-disjoint. Similarly, we have  $d(C_j) \le SH$  for any  $j \in [\nu]$ . Thus, we have

$$H \ge \frac{d(R_i)}{S}, \frac{d(C_j)}{S}$$

for any  $i, j \in [S]$ , and we have the theorem.

In Figs. 10 and 11, let  $t_k$  and  $b_k$  be the terminals of  $N_k$  on the top and bottom layers, respectively. In Fig. 10,  $\{t_9, t_{10}, t_{13}, t_{14}, b_5, b_6, b_1, b_2\} \subseteq V(R_2)$ , and for each  $k \in \{3, 4, 7, 8, 11, 12\}$ ,  $t_k$  and  $b_k$  are on different sides of  $R_2$ . Therefore, we have  $d(R_2) = 14$ . Since

$$\max \{ \max\{d(C_j) \mid j \in [S]\}, \max\{d(R_i) \mid i \in [S]\} \}$$
  
=  $d(R_2)$   
= 14.

we have  $\Delta_{\text{glo}}(N_a) = 14/4$ . In Fig. 11, terminals  $t_k$  and  $b_k$  for each  $k \in \{1, 2, 3, 4\}$  are on  $C_2$ , and terminals  $t_k$  and  $b_k$  for each  $k \in \{5, 6\}$  are on different sides of  $C_2$ . Therefore,

$$d(C_2) = |\{t_k, b_k \mid k \in \{1, 2, 3, 4\}\} \cup \{N_5, N_6\}| = 10,$$

and we have  $\Delta_{\text{glo}}(\mathcal{N}_b) \geq 10/4$ .

Our final lower bound is the *local density*  $\Delta_{loc}(N)$  which is defined as follows. Let Q be a cycle on top layer  $L_t$ , Q' be the corresponding cycle on bottom layer  $L_b$ , and  $Q_i$  be the corresponding cycle on the *i*-th layer defined by z = i. Notice that  $V(Q_i) = \{(x, y, i) \mid (x, y, H) \in V(Q)\}, Q_H = Q$ , and  $Q_1 = Q'$ . Let T(Q) be the set of terminals on Q, T(Q') be the set of terminal outside of Q on  $L_t$  and a terminal outside of Q on  $L_b$ . The following is immediate.

**Lemma 5:** A wire of any net in  $N_Q[Q']$  contains a vertex of  $\bigcup_{i=1}^{H} V(Q_i)$ .

Let d(Q) [d(Q')] be the sum of the number of terminals on Q[Q'] and the number of 2-nets which have a terminal inside of Q [Q'] on  $L_t [L_b]$ , and a terminal outside of Q' [Q] on  $L_b$ [ $L_t$ ], that is,

$$d(Q) = |\mathcal{N}(Q)| + |T(Q)|, \text{ and}$$
 (7)

$$d(Q') = |\mathcal{N}(Q')| + |T(Q')|.$$
(8)

Notice that

$$T(Q) \subseteq V(Q)$$
, and (9)

$$T(Q') \subseteq V(Q'). \tag{10}$$

We define that:

$$\Delta_{\text{loc}}(\mathcal{N}) = \max\left\{\frac{d(Q) + d(Q')}{|V(Q)|} \mid Q: \text{ a cycle on } L_t\right\}.$$

**Theorem 5:** If  $\mathcal{N}$  is routable in G then  $H \ge \lceil \Delta_{\text{loc}}(\mathcal{N}) \rceil$ .

*Proof.* From Lemma 5, (7), (8), (9), and (10), we have

$$d(Q) + d(Q') \le \left| \bigcup_{i=1}^{H} V(Q_i) \right| = H|V(Q)|$$

since wires are vertex-disjoint. Thus, we have

$$H \ge \frac{d(Q) + d(Q')}{|V(Q)|}$$

for any cycle Q on the top layer, and we have the theorem.

In Fig. 10, if I(Q) is the set of inner vertices of Q on  $L_t$ , we have |I(Q)| < |V(Q)|/2, since S = 4. Therefore,  $d(Q) \le |V(Q)| + |I(Q)| < 3|V(Q)|/2$ . Similarly, we have d(Q') < 3|V(Q')|/2. Thus, we have  $\Delta_{loc}(N_a) < 3/2 + 3/2 = 3$ . In Fig. 11, we have d(Q) < |V(Q)| and d(Q') < |V(Q')| for any cycle Q and Q' on  $L_t$  and  $L_b$ , respectively. Therefore,  $\Delta_{loc}(N_b) < 2$ .

#### 4.2 Comparisons

We can show that there are instances  $N_{\text{lay}}$ ,  $N_{\text{glo}}$ , and  $N_{\text{loc}}$  such that  $\Delta_{\text{lay}}(N_{\text{lay}})$  dominates  $\Delta_{\text{glo}}(N_{\text{lay}})$  and  $\Delta_{\text{loc}}(N_{\text{lay}})$ ,  $\Delta_{\text{glo}}(N_{\text{glo}})$  dominates  $\Delta_{\text{lay}}(N_{\text{glo}})$  and  $\Delta_{\text{loc}}(N_{\text{glo}})$ , and  $\Delta_{\text{loc}}(\mathcal{N}_{\text{loc}})$  dominates  $\Delta_{\text{lay}}(\mathcal{N}_{\text{loc}})$  and  $\Delta_{\text{loc}}(\mathcal{N}_{\text{loc}})$ .

For  $\mathcal{N}_a$  in Fig. 10,  $\Delta_{\text{lay}}(\mathcal{N}_a)$  dominates  $\Delta_{\text{glo}}(\mathcal{N}_a)$  and  $\Delta_{\text{loc}}(\mathcal{N}_a)$ , since  $\Delta_{\text{lay}}(\mathcal{N}_a) = 28$ ,  $\Delta_{\text{glo}}(\mathcal{N}_a) = 14/4$ , and  $\Delta_{\text{loc}}(\mathcal{N}_a) < 3$  as we have calculated. For  $\mathcal{N}_b$  in Fig. 11,  $\Delta_{\text{glo}}(\mathcal{N}_b)$  dominates  $\Delta_{\text{lay}}(\mathcal{N}_b)$  and  $\Delta_{\text{loc}}(\mathcal{N}_b)$ , since  $\Delta_{\text{glo}}(\mathcal{N}_b) \ge 10/4$ ,  $\Delta_{\text{lay}}(\mathcal{N}_b) \le 1$ , and  $\Delta_{\text{loc}}(\mathcal{N}_b) < 2$  as we have calculated.

The proof of Theorem 8 shown in the next section provides a set of nets N such that  $\Delta_{loc}(N)$  dominates  $\Delta_{glo}(N)$  and  $\Delta_{lay}(N)$  if v is sufficiently large.

It is interesting to note that  $\Delta_{loc}(N)$  asymptotically dominates  $\Delta_{glo}(N)$  for any N as shown in the following.

**Theorem 6:**  $\Delta_{\text{glo}}(\mathcal{N}) = O(\Delta_{\text{loc}}(\mathcal{N}))$  for any instance if the layer is square.

*Proof.* For any  $x, y \in [S]$ , let  $X_{x,h}$  and  $Y_{y,h}$  be cycles induced by vertex sets

$$V(X_{x,h}) = \{(j, 1, h) \mid 1 \le j \le x\} \cup \{(j, S, h) \mid 1 \le j \le x\} \cup \{(1, i, h) \mid 1 \le i \le S\} \cup \{(x, i, h) \mid 1 \le i \le S\}, \text{ and} V(Y_{y,h}) = \{(1, i, h) \mid 1 \le i \le y\} \cup \{(S, i, h) \mid 1 \le i \le y\} \cup \{(j, 1, h) \mid 1 \le j \le S\}, \{(j, y, h) \mid 1 \le j \le S\},$$

respectively. By definition, we have

$$d(X_{x,h}) \ge d(C_x), \quad d(Y_{y,h}) \ge d(R_y), \text{ and}$$
  
 $|V(X_{x,h})|, |V(Y_{y,h})| \le 4S.$ 

Therefore, we have

$$\Delta_{\text{glo}}(N)$$

$$= \max\left\{\frac{\max\left\{d(R_{i}) \mid i \in [S]\right\}}{S}, \frac{\max\left\{d(C_{j}) \mid j \in [S]\right\}}{S}\right\}$$

$$\leq \max\left\{\max\left\{\frac{d(X_{x,H}) + d(X_{x,1})}{|V(X_{x,H})|/4} \mid x \in [S]\right\}, \\ \max\left\{\frac{d(Y_{y,H}) + d(Y_{y,1})}{|V(Y_{y,H})|/4} \mid y \in [S]\right\}\right\}$$

$$\leq \max\left\{\frac{d(Q) + d(Q')}{|V(Q)|/4} \mid Q : \text{a cycle on } L_{t}.\right\}$$

$$= 4\Delta_{\text{loc}}(\mathcal{N}),$$

and we obtain the theorem.

#### 4.3 Sparse Instances

Suppose that G is a  $(2\sqrt{v}, 2\sqrt{v}, H)$ -channel with a sparse set  $\mathcal{N} = \{N_k \mid i \in [v]\}$  of 2-nets, and  $N_k = \{(x_k^t, y_k^t, H), (x_k^b, y_k^b, 1)\}$ , where  $x_k^t, y_k^t, x_k^b$ , and  $y_k^b$  are odd integers. We have shown in Sect. 3 that any sparse instance  $\mathcal{N}$  is routable in G if  $H \ge 3\sqrt{v} + 1$ .

It follows from Theorem 6 above and Theorem 7 below that  $\Delta_{loc}(N)$  asymptotically dominates  $\Delta_{lay}(N)$  and  $\Delta_{glo}(N)$ for sparse instances. **Theorem 7:**  $\Delta_{\text{lay}}(\mathcal{N}) = O(\Delta_{\text{glo}}(\mathcal{N}))$  for any sparse instance.

*Proof.* It is easy to see the following.

$$3\nu\Delta_{\text{lay}}(\mathcal{N}) = \sum_{k=1}^{\nu} \left( |x_k^t - x_k^b| + |y_k^t - y_k^b| \right)$$
  
$$\leq \sum_{j=1}^{2\sqrt{\nu}} d(C_j) + \sum_{i=1}^{2\sqrt{\nu}} d(R_i)$$
  
$$\leq 2\sum_{i=1}^{2\sqrt{\nu}} 2\sqrt{\nu}\Delta_{\text{glo}}(\mathcal{N})$$
  
$$= 8\nu\Delta_{\text{glo}}(\mathcal{N}).$$

It follows that  $\Delta_{\text{lay}}(\mathcal{N}) \leq \frac{8}{3} \Delta_{\text{glo}}(\mathcal{N})$ , and we have the theorem.  $\Box$ 

On the other hand, there are sparse instances N such that neither  $\Delta_{lay}(N)$  nor  $\Delta_{glo}(N)$  asymptotically dominates  $\Delta_{loc}(N)$  as shown below.

**Theorem 8:** There exist sparse instances such that  $\Delta_{\text{loc}}(\mathcal{N}) = \omega(\Delta_{\text{glo}}(\mathcal{N})).$ 

*Proof.* Let  $Q_1$  and  $Q_2$  be disjoint square cycles on  $L_t$  such that neither is inside of the other, and  $|V(Q_1)| = |V(Q_2)| = 8\lfloor \sqrt[4]{\nu} \rfloor - 4$ . (See Fig. 12.) Suppose that each 2-net with a terminal inside  $Q_1 [Q_2]$  on  $L_t$  has the other inside  $Q'_2 [Q'_1]$  on  $L_b$ , and for every other 2-net, the terminals on  $L_t$  and  $L_b$  have the same *x*- and *y*-coordinates. Since  $d(Q_1) = d(Q_2) = \lfloor \sqrt[4]{\nu} \rfloor^2 + 2\lfloor \sqrt[4]{\nu} \rfloor - 1$ ,  $\Delta_{\text{loc}}(\mathcal{N}) = \Omega(\lfloor \sqrt[4]{\nu} \rfloor)$ . On the other hand,  $\Delta_{\text{glo}}(\mathcal{N}) \leq 2$  as easily seen, and we have the theorem.

Finally, we show the following which complements Theorem 2.

**Theorem 9:** There exists a sparse set of 2-nets N that cannot be routed in a  $(2\sqrt{\nu}, 2\sqrt{\nu}, 2\sqrt{\nu}/3 - 1)$ -channel.

*Proof.* For  $i \in [\sqrt{\nu}]$ ,  $j \in [\sqrt{\nu}]$ , and  $k = (j - 1)\sqrt{\nu} + i$ , define that

$$\begin{split} X_k^{(1)} &= 2j - 1, \\ X_k^{(H)} &= \begin{cases} 2j + \sqrt{\nu} - 1 & \text{if } j \le \sqrt{\nu} \\ 2j - \sqrt{\nu} - 1 & \text{if } j \ge \sqrt{\nu} + 1, \end{cases} \\ Y_k^{(1)} &= 2i - 1, \end{split}$$



Fig. 12 An example of a set N such that  $\Delta_{loc}(N)$  dominates  $\Delta_{glo}(N)$  and  $\Delta_{lay}(N)$ .

$$Y_k^{\langle H \rangle} = \begin{cases} 2i + \sqrt{\nu} - 1 & \text{if } i \le \sqrt{\nu}, \text{ and} \\ 2i - \sqrt{\nu} - 1 & \text{if } i \ge \sqrt{\nu} + 1. \end{cases}$$

By the definitions of  $X_k^{(1)}$ ,  $X_k^{(H)}$ ,  $Y_k^{(1)}$ , and  $Y_k^{(H)}$ , we have

$$\begin{aligned} \left| X_k^{\langle 1 \rangle} - X_k^{\langle H \rangle} \right| &= \sqrt{\nu}, \text{ and} \\ \left| Y_k^{\langle 1 \rangle} - Y_k^{\langle H \rangle} \right| &= \sqrt{\nu}, \end{aligned}$$

i.e.,

$$\sum_{k=1}^{\nu} \left( \left| X_{k}^{\langle 1 \rangle} - X_{k}^{\langle H \rangle} \right| + \left| Y_{k}^{\langle 1 \rangle} - Y_{k}^{\langle H \rangle} \right| \right) = 2\nu \sqrt{\nu}.$$
(11)

Let  $\mathcal{N} = \{N_k \mid k \in [\nu]\}$  be a set of  $\nu$  2-nets such that  $N_k = \{(X_k^{\langle H \rangle}, Y_k^{\langle H \rangle}, H), (X_k^{\langle 1 \rangle}, Y_k^{\langle 1 \rangle}, 1)\}$ . From (11), we have

$$\Delta_{\text{lay}}(\mathcal{N}) = \frac{2\nu\sqrt{\nu}}{4\nu-\nu} = \frac{2\sqrt{\nu}}{3}.$$

Thus, N cannot be routed in a  $(2\sqrt{\nu}, 2\sqrt{\nu}, 2\sqrt{\nu}/3 - 1)$ channel, and we have the theorem.

#### 5. Concluding Remarks

We have shown that 3-D CHANNEL ROUTING is NP-hard. In fact, we can show that 3-D CHANNEL ROUTING is NP-complete. It is shown in [20], [21] that 3-D channel routing is indeed in NP.

The Manhattan model is one of the most popular 2-D channel routing models for practitioners. Szymanski [18] proved that the corresponding decision problem is NP-hard, while the complexity of the problem for 2-nets has been open as mentioned in [13]. The knock-knee model is another popular 2-D channel routing model. Sarrafzardeah [17] proved that the corresponding decision problem is NP-hard, while the complexity of the problem for 2-nets is also open. It is interesting to note that 3-D CHANNEL ROUT-ING is NP-hard even for 2-nets as we have shown in this paper.

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