

## LETTER

## On-Line Multicasting in All-Optical Networks

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**SUMMARY** We consider the routing for a multicast in a WDM all-optical network. We prove a min-max theorem on the number of wavelengths necessary for routing a multicast. Based on the min-max theorem, we propose an efficient on-line algorithm for routing a multicast.

**key words:** all-optical network, wavelength division multiplexing, multicast, on-line algorithm

## 1. Introduction

A WDM (Wavelength Division Multiplexing) all-optical network consists of routing nodes interconnected by point-to-point unidirectional fiber-optic links, which support a certain number of wavelengths. The same wavelength on two input ports cannot be routed to the same output port due to the interference. An optical routing assigns a path and a wavelength for each communication request in such a way that no two paths traversing a common link are assigned the same wavelength. A fundamental problem for WDM all-optical networks is to minimize the number of wavelengths necessary for the optical routing. This paper considers the on-line optical routing for a special collection of communication requests called a multicast.

A WDM all-optical network is modeled as a symmetric digraph (directed graph)  $G$  with vertex set  $V(G)$  and arc (directed edge) set  $A(G)$  such that if  $(u, v) \in A(G)$  then  $(v, u) \in A(G)$ , where the vertices represent the routing nodes and each arc represents a point-to-point unidirectional fiber-optic link connecting a pair of routing nodes.

Let  $P(x, y)$  denote a dipath (directed path) in  $G$  from the vertex  $x$  to  $y$  which consists of consecutive arcs beginning at  $x$  and ending at  $y$ . A request is an ordered pair of vertices  $(x, y)$  in  $G$  corresponding to a message to be sent from  $x$  to  $y$ , and an instance  $I$  is a collection (multiset) of requests. A routing for an instance  $I$  is a collection of dipaths  $R = \{P(x, y) | (x, y) \in I\}$ .

Given a symmetric digraph  $G$ , an instance  $I$ , and a routing  $R$  for  $I$ ,  $\omega(G, I, R)$  is the minimum number of wavelengths that can be assigned to the dipaths in

$R$ , so that no two dipaths sharing an arc have the same wavelength. Let  $\omega(G, I)$  denote the smallest  $\omega(G, I, R)$  over all routings  $R$  for  $I$ . The load of an arc  $\alpha \in A(G)$  in  $R$ , denoted by  $\pi(G, I, R, \alpha)$ , is the number of dipaths in  $R$  containing  $\alpha$ . Let  $\pi(G, I, R)$  denote the largest  $\pi(G, I, R, \alpha)$  over all arcs  $\alpha \in A(G)$ , and  $\pi(G, I)$  denote the smallest  $\pi(G, I, R)$  over all routings  $R$  for  $I$ . It is known that computing  $\omega(G, I)$  and  $\pi(G, I)$  is NP-hard in general [2]. It is not difficult to see that  $\omega(G, I) \geq \pi(G, I)$  for an instance  $I$  in a symmetric digraph  $G$  and that the inequality can be strict in general [2].

Beauquier, Hell, and Perennes [3] proved that for a multicast  $I$  in a symmetric digraph  $G$ ,  $\omega(G, I) = \pi(G, I)$  and both  $\omega(G, I)$  and  $\pi(G, I)$  can be computed in polynomial time. An instance  $I$  is called a multicast if  $I$  is of the form  $\{(x, y) | y \in Y\}$  for a fixed vertex  $x \in V(G)$ , called the source, and a collection  $Y$  of vertices in  $V(G)$ , called the destinations.

This paper shows a min-max equality on  $\omega(G, I)$  for a multicast  $I$  in a symmetric digraph  $G$  by means of the cut in  $G$ . For a digraph  $G$  and a nonempty proper subset  $S \subset V(G)$ , a cut  $(S, \bar{S})$  is the set of arcs beginning in  $S$  and ending in  $\bar{S}$ , where  $\bar{S} = V(G) - S$ . For a multicast  $I = \{(x, y) | y \in Y\}$  and a cut  $(X, \bar{X})$  with  $x \in X \subset V(G)$ , let  $\mu(G, I, X)$  denote  $|Y \cap \bar{X}| / |(X, \bar{X})|$ , and  $\mu(G, I)$  denote the largest  $\mu(G, I, X)$  over all cuts  $(X, \bar{X})$  with  $x \in X \subset V(G)$ . Notice that  $\mu(G, I, X)$  is a lower bound on the average load of an arc in  $(X, \bar{X})$  for any routing for  $I$ . We prove a min-max equality that  $\omega(G, I) = \mu(G, I)$ , which is used as a basis for on-line multicasting. Let  $\delta(x)$  denote the outdegree of  $x$  and  $\lambda(x)$  denote  $\min\{|(X, \bar{X})| | x \in X \subset V(G)\}$ . Notice that  $\delta(x) \geq \lambda(x)$ . If  $I$  is a broadcast, that is  $I = \{(x, y) | y \in V(G) - x\}$  and  $\delta(x) = \lambda(x)$  then our min-max equality implies that  $\omega(G, I) = \lceil (|V(G)| - 1) / \delta(x) \rceil$ , which is essentially Theorem 3.1 in [4] proved by Bermond, Gargano, Perennes, Rescigno, and Vaccaro.

Given a symmetric digraph  $G$  and a sequence of requests  $(x_i, y_i)$ , an on-line algorithm assigns a dipath  $P(x_i, y_i)$  and a wavelength to  $P(x_i, y_i)$ , so that no two dipaths sharing an arc are assigned the same wavelength. The performance measure for an on-line algorithm is the competitive ratio defined as the worst-case ratio over all request sequences between the number of wavelengths used by the on-line algorithm and the optimal number of wavelengths necessary on the same

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sequence. Bartal and Leonardi [1] showed on-line algorithms with competitive ratio of  $O(\log N)$  for any instances in  $N$ -vertex digraphs associated with meshes, trees, and trees of rings, where the digraph associated with a graph  $H$  is the symmetric digraph obtained when each edge  $e$  of  $H$  is replaced by two oppositely oriented arcs with the same ends as  $e$ . They also proved a matching lower bound of  $\Omega(\log N)$  for digraphs associated with meshes, and a lower bound of  $\Omega(\log N / \log \log N)$  for digraphs associated with trees and trees of rings [1].

We show here an on-line algorithm for a multicast  $I = \{(x, y) | y \in Y\}$  in a symmetric digraph  $G$ . We prove that the competitive ratio of our algorithm is  $\lceil \delta(x) / \lambda(x) \rceil$ . It follows that if  $\delta(x) = O(1)$  then the competitive ratio of our algorithm is  $O(1)$ . Moreover, if  $\delta(x) = \lambda(x)$  then our algorithm is optimal. We also show a complementary result that if  $\delta(x) > \lambda(x)$  then there is no optimal on-line algorithm. Moreover, we show that the competitive ratio of any on-line algorithm is at least  $4/3$ . We also consider the dynamic multicasting.

## 2. Off-Line Multicasting

We prove in this section the following min-max equality, which will be used in the subsequent sections.

**Theorem 1:**  $\omega(G, I) = \mu(G, I)$  for a multicast  $I$  in a symmetric digraph  $G$ .

### 2.1 Proof of Theorem 1

Let  $G$  be a symmetric digraph and  $I = \{(x, y) | y \in Y\}$  be a multicast in  $G$ .

#### 2.1.1 Proof of $\omega(G, I) \geq \mu(G, I)$

It is well-known and easily verified that

$$\omega(G, I) \geq \pi(G, I). \quad (1)$$

Since  $\mu(G, I, X)$  is a lower bound on the average load of an arc in a cut  $(X, \bar{X})$  with  $x \in X \subset V(G)$  for any routing  $R$  for  $I$ , we have

$$\pi(G, I, R) \geq \mu(G, I, X)$$

for any routing  $R$  for  $I$  and any cut  $(X, \bar{X})$  with  $x \in X \subset V(G)$ . Thus, it follows that

$$\pi(G, I) \geq \mu(G, I). \quad (2)$$

Combining (1) and (2), we have

$$\omega(G, I) \geq \mu(G, I).$$

#### 2.1.2 Proof of $\omega(G, I) \leq \mu(G, I)$

It is proved in [3] that for a multicast  $I = \{(x, y) | y \in Y\}$  in a symmetric digraph  $G$  we have

$$\omega(G, I) = \pi(G, I), \quad (3)$$

by using flow networks derived from  $G$ .

In a flow network, we denote by  $c(u, v)$  the capacity of an arc  $(u, v)$ , and by  $c(T, \bar{T})$  the capacity of a cut  $(T, \bar{T})$ . Although  $Y$  is a collection (multiset) in general, we assume without loss of generality that  $Y$  is just a set, as mentioned in [3].

In order to compute  $\pi(G, I)$  the following flow network  $F_p$  is introduced in [3]. Let  $s$  and  $t$  be two new vertices which will be the source and sink in  $F_p$ , respectively. The flow network  $F_p$  is defined as follows:

$$\begin{aligned} V(F_p) &= \{s, t\} \cup V(G) \\ A(F_p) &= \{(s, x)\} \cup A(G) \cup \left( \bigcup_{y \in Y} \{(y, t)\} \right) \\ c(s, x) &= \infty \\ c(u, v) &= p \text{ for all } (u, v) \in A(G) \\ c(y, t) &= 1 \text{ for all } y \in Y. \end{aligned}$$

The theorem below directly follows from the definition.

**Theorem I:** [3]  $\pi(G, I) \leq p$  if and only if  $F_p$  has a flow of value  $|Y|$ .

By (3) and Theorem I above, it suffices to show that  $F_{\mu(G, I)}$  has a flow of value  $|Y|$ . We prove this by showing that any cut in  $F_{\mu(G, I)}$  separating  $s$  and  $t$  has capacity at least  $|Y|$ . Any cut in  $F_{\mu(G, I)}$  separating  $s$  and  $t$  can be represented as  $(S \cup \{s\}, \bar{S} \cup \{t\})$  for a subset  $S$  of  $V(G)$  and  $\bar{S} = V(G) - S$ . It is easy to see that

$$\begin{aligned} c(S \cup \{s\}, \bar{S} \cup \{t\}) &= \begin{cases} |Y \cap S| + \mu(G, I) \cdot |(S, \bar{S})| & \text{if } x \in S \\ \infty & \text{if } x \in \bar{S} \end{cases} \end{aligned}$$

where  $(S, \bar{S})$  is a cut in  $G$ . It follows that we may assume that  $x \in S$ . Then we have

$$\begin{aligned} c(S \cup \{s\}, \bar{S} \cup \{t\}) &= |Y \cap S| + \mu(G, I) \cdot |(S, \bar{S})| \\ &= |Y \cap S| \\ &\quad + \max \left\{ \left\lceil \frac{|Y \cap \bar{X}|}{|(X, \bar{X})|} \right\rceil \mid x \in X \subset V(G) \right\} \cdot |(S, \bar{S})| \\ &\geq |Y \cap S| + \left\lceil \frac{|Y \cap \bar{S}|}{|(S, \bar{S})|} \right\rceil \cdot |(S, \bar{S})| \\ &\geq |Y \cap S| + \frac{|Y \cap \bar{S}|}{|(S, \bar{S})|} \cdot |(S, \bar{S})| \\ &= |Y \cap S| + |Y \cap \bar{S}| = |Y|, \end{aligned}$$

as desired.

## 3. On-Line Multicasting

### 3.1 Upper Bounds

Let  $G$  be a symmetric digraph, and  $(x, y_1), (x, y_2), \dots,$

$(x, y_j), \dots$  be a sequence of multicast requests in  $G$ . Let  $I_j$  denote the collection  $\{(x, y_1), (x, y_2), \dots, (x, y_j)\}$ , and  $Y_j$  denote the collection  $\{y_1, y_2, \dots, y_j\}$ . We assume without loss of generality that  $x$  is not a cut-vertex in  $G$ . We also assume that the wavelengths are labeled with positive integers. Our on-line algorithm is based on a classic theorem of Edmonds [5]. For a vertex  $u$  of a digraph  $G$ ,  $u$ -arborescence  $H(u)$  in  $G$  is an acyclic spanning subdigraph of  $G$  such that for every vertex  $v \in V(G)$  there is exactly one dipath in  $H(u)$  from  $u$  to  $v$ .

**Theorem II:** [5] For a digraph  $G$  and a vertex  $u \in V(G)$ , the maximum number of arc-disjoint  $u$ -arborescences in  $G$  is equal to  $\lambda(u)$ .

Let  $\mathcal{H} = \{H_1(x), H_2(x), \dots, H_{\lambda(x)}(x)\}$  be a set of arc-disjoint  $x$ -arborescences in  $G$ . For each request, our on-line algorithm, called ARB, assigns a dipath in an  $x$ -arborescence in  $\mathcal{H}$ . Given a request  $(x, y_j)$ , ARB finds an  $x$ -arborescence  $H_k(x)$  such that the number of dipaths in  $H_k(x)$  assigned to the existing requests is minimal, assigns the unique dipath  $P(x, y_j)$  in  $H_k(x)$ , and assigns the lowest available wavelength to  $P(x, y_j)$ .

**Theorem 2:** The competitive ratio of ARB is  $\lceil \delta(x)/\lambda(x) \rceil$ .

**Proof:** From Theorem 1, we have that for any  $j$ ,

$$\begin{aligned} \omega(G, I_j) &= \mu(G, I_j) \\ &= \max \left\{ \left\lceil \frac{|Y_j \cap \overline{X}|}{|(X, \overline{X})|} \right\rceil \mid x \in X \subset V(G) \right\} \\ &\geq \left\lceil \frac{|Y_j \cap (V(G) - \{x\})|}{|(\{x\}, V(G) - \{x\})|} \right\rceil \\ &= \left\lceil \frac{|Y_j|}{\delta(x)} \right\rceil \\ &\geq \frac{|Y_j|}{\delta(x)}. \end{aligned}$$

Let  $\omega(G, I_j, \text{ALG})$  denote the number of wavelengths used by an on-line algorithm ALG for  $I_j$ . We have that

$$\begin{aligned} \omega(G, I_j, \text{ARB}) &= \left\lceil \frac{|Y_j|}{\lambda(x)} \right\rceil \\ &\leq \left\lceil \frac{\omega(G, I_j) \cdot \delta(x)}{\lambda(x)} \right\rceil \\ &\leq \left\lceil \frac{\delta(x)}{\lambda(x)} \right\rceil \cdot \omega(G, I_j), \end{aligned}$$

as desired.  $\square$

The following corollaries are immediate. An on-line algorithm ALG is said to be optimal for  $G$  if  $\omega(G, I_j, \text{ALG}) = \omega(G, I_j)$  for any  $j$ .

**Corollary 1:** If  $\delta(x)$  is  $O(1)$  then the competitive ratio of ARB is  $O(1)$ .

**Corollary 2:** If  $\delta(x) = \lambda(x)$  then ARB is optimal for  $G$ .

**Corollary 3:** ARB is optimal for digraphs associated with trees, cycles, tori, hypercubes, and cube-connected cycles.

### 3.2 Lower Bounds

The following is a complementary result to Corollary 2.

**Theorem 3:** If  $\delta(x) > \lambda(x)$  then there is no on-line algorithm optimal for  $G$ .

**Proof:** We prove the theorem by contradiction. Let  $G$  be a symmetric digraph, and  $x$  be a vertex in  $G$  with  $\delta(x) > \lambda(x)$ . Assume that there is an on-line algorithm ALG optimal for  $G$ . Let  $(X, \overline{X})$  be a cut in  $G$  such that  $x \in X \subset V(G)$  and  $|(X, \overline{X})| = \lambda(x)$ , and  $v$  be a vertex in  $\overline{X}$ . We denote the arcs with tail  $x$  by  $(x, u_1), (x, u_2), \dots, (x, u_{\delta(x)})$ . We consider the following sequence of requests:

$$(x, u_1), (x, u_2), \dots, (x, u_{\delta(x)}), \underbrace{(x, v), (x, v), \dots, (x, v)}_{\lambda(x)+1}.$$

Since ALG is optimal for  $G$ , ALG assigns for the requests  $(x, u_i)$  arc-disjoint dipaths  $P(x, u_i)$  and the same wavelength, say  $w$ , to the dipaths  $P(x, u_i)$  ( $1 \leq i \leq \delta(x)$ ). Notice that each arc  $(x, u_i)$  is contained in the dipaths assigned wavelength  $w$  ( $1 \leq i \leq \delta(x)$ ). Since  $|(X, \overline{X})| = \lambda(x)$ , ALG uses at least two more wavelengths different from  $w$  for the last  $\lambda(x) + 1$  requests of  $(x, v)$ . Thus, ALG uses at least 3 wavelengths for the request sequence. On the other hand, we have the following off-line algorithm. There is a set  $\mathcal{A}$  of  $\lambda(x)$  arc-disjoint  $x$ -arborescences in  $G$  by Theorem II. For each of  $\lambda(x)$  requests of  $(x, v)$ , we assign a dipath in distinct  $x$ -arborescence in  $\mathcal{A}$ , and assign the same wavelength, say  $w$ , to the dipaths. Since  $\delta(x) > \lambda(x)$ , there exists some  $u_i$  ( $1 \leq i \leq \delta(x)$ ) such that no dipaths above pass through  $u_i$ . Since  $x$  is not a cut-vertex, there is a dipath  $P(u_i, v)$  that does not pass through  $x$ . For the remaining request of  $(x, v)$ , we assign a dipath consisting of arc  $(x, u_i)$  and  $P(u_i, v)$ , and assign a wavelength different from  $w$ , say  $w'$ , to the dipaths. Then we can assign a dipath consisting of an arc  $(x, u_j)$  with wavelength  $w'$  for every requests  $(x, u_j)$  ( $j \neq i$ ), and arc  $(x, u_i)$  with wavelength  $w$  for request  $(x, u_i)$ . In total, we use only 2 wavelengths for the request sequence, a contradiction. Thus we have the theorem.  $\square$

By Corollary 2 and Theorem 3 above, we have the following corollary.

**Corollary 4:** There is an on-line algorithm optimal for  $G$  if and only if  $\delta(x) = \lambda(x)$ .

We can show a general lower bound as follows. Let  $M$  be a mesh with  $V(M) = \{0, 1, 2\}^2$ . The vertices  $ij$

and  $i'j'$  are adjacent if and only if  $|i - i'| + |j - j'| = 1$ . Let  $G_M$  be the digraph associated with  $M$ .

**Theorem 4:** The competitive ratio of any on-line algorithm for  $G_M$  is at least  $4/3$ .

**Proof:** Let  $u_1 = 01$ ,  $u_2 = 10$ ,  $u_3 = 12$ ,  $u_4 = 21$ ,  $v = 00$ , and  $x = 11$ . Let ALG be any on-line algorithm for  $G_M$ . For any positive integer  $l$ , we consider the following sequence of  $4l$  requests  $I_{4l}$ :

$$\underbrace{(x, u_1), \dots, (x, u_1)}_l, \underbrace{(x, u_2), \dots, (x, u_2)}_l, \underbrace{(x, u_3), \dots, (x, u_3)}_l, \underbrace{(x, u_4), \dots, (x, u_4)}_l. \quad (4)$$

If  $\omega(G_M, I_{4l}, \text{ALG}) \geq 4l/3$  then we are done, because  $\omega(G_M, I_{4l}) = l$  as easily seen, and we have

$$\omega(G_M, I_{4l}, \text{ALG}) \geq \frac{4}{3}l = \frac{4}{3}\omega(G_M, I_{4l}).$$

If  $\omega(G_M, I_{4l}, \text{ALG}) < 4l/3$  then we consider the following sequence of additional  $4l$  requests  $I'_{4l}$ :

$$\underbrace{(x, v), (x, v), \dots, (x, v)}_{4l}. \quad (5)$$

Suppose that ALG uses  $l + i$  ( $0 \leq i < l/3$ ) wavelengths for the sequence (4), and let  $W = \{w_1, w_2, \dots, w_{l+i}\}$  be the set of wavelengths used for the sequence (4). Since the outdegree of  $x$  is 4, the maximum number of requests for which we can assign wavelengths in  $W$  is  $4(l + i)$ . Since the number of requests in the sequence (4) is  $4l$ , ALG can use the wavelengths in  $W$  for at most  $4(l + i) - 4l = 4i$  requests in the sequence (5). Since the indegree of  $v$  is 2, ALG needs at least  $(4l - 4i)/2 = 2l - 2i$  additional wavelengths not in  $W$  for the sequence (5). Thus, ALG uses at least  $(l + i) + (2l - 2i) = 3l - i$  wavelengths for the concatenation of the sequences (4) and (5). Since  $i < l/3$ , we have

$$\omega(G_M, I_{4l} \cup I'_{4l}, \text{ALG}) \geq 3l - i > 3l - \frac{1}{3}l = \frac{8}{3}l.$$

On the other hand, it is easy to see that  $\omega(G_M, I_{4l} \cup I'_{4l}) = 2l$ . Thus we have

$$\omega(G_M, I_{4l} \cup I'_{4l}, \text{ALG}) > \frac{4}{3}\omega(G_M, I_{4l} \cup I'_{4l}),$$

as desired.  $\square$

Notice that  $\omega(G_M, I, \text{ARB}) \leq 2\omega(G_M, I)$  for any multicast  $I$ .

Our general upper bound for the competitive ratio is  $\lceil \delta(x)/\lambda(x) \rceil$ , and general lower bound is  $4/3$ . It is an interesting open problem to close the gap between upper and lower bounds above.

#### 4. Dynamic Multicasting

In the dynamic multicasting, a sequence of request arrivals and terminations is given for a multicast  $I =$

$\{(x, y) | y \in Y\}$ . A dynamic algorithm assigns a dipath  $P(x, y_i)$  and a wavelength to  $P(x, y_i)$ , so that no two dipaths sharing an arc are assigned the same wavelength if a request  $(x, y_i)$  arrives, and deletes  $P(x, y_i)$  together with the wavelength assigned if a request  $(x, y_i)$  terminates. Let  $I_j$  denote a collection of the existing requests just after  $j$ th request arrival or termination in the sequence. We denote by  $\omega(G, x, L, \text{ALG}, I_j)$  the number of wavelengths used by a dynamic algorithm ALG for  $I_j$  provided that  $\mu(G, I_j) \leq L$  for any  $j$ . Let  $\omega(G, x, L, \text{ALG})$  denote  $\max_j \omega(G, x, L, \text{ALG}, I_j)$  and  $\omega(G, x, L)$  denote the smallest  $\omega(G, x, L, \text{ALG})$  over all dynamic algorithms ALG. Notice that  $\omega(G, x, L) \geq L$ .

Our dynamic algorithm ARB' is obtained from ARB by simply adding the operation of deleting a path for the termination of the corresponding request. The following results are immediate from the corresponding results in the previous section.

**Theorem 5:**

$$\omega(G, x, L, \text{ARB}') \leq \left\lceil \frac{L \cdot \delta(x)}{\lambda(x)} \right\rceil.$$

**Corollary 5:** If  $\delta(x) = O(1)$  then  $\omega(G, x, L, \text{ARB}') = O(L)$ .

**Theorem 6:**  $\omega(G, x, L) = L$  if and only if  $\delta(x) = \lambda(x)$ .

**Theorem 7:**

$$\omega(G_M, x, L) \geq \frac{4}{3}L.$$

It should be noted that the performance of dynamic optical routing is considerably less than that of on-line optical routing in general, as mentioned in [6]. Our results indicate that the performance of dynamic multicasting is comparable to that of on-line multicasting.

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